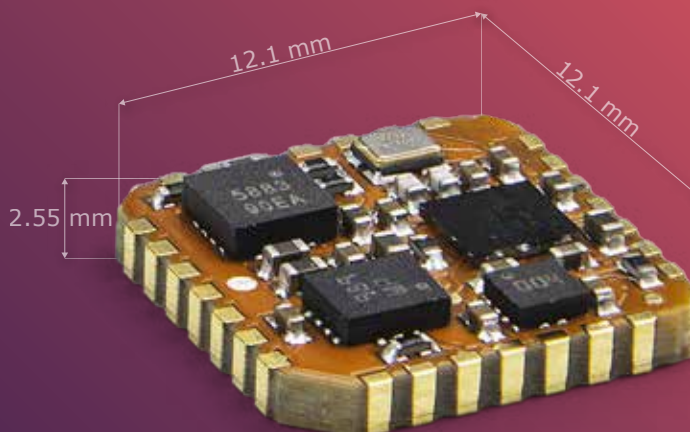


MTi-7

- **Miniature form factor (12x12 mm)**
- **Easy integration**
- **Development Kit available**

The MTi-7 is a miniature GNSS/INS as a 12.1 x 12.1 mm module with an interface to an external GNSS receiver. The Xsens optimized strapdown algorithm (AttitudeEngine™) performs high-speed dead-reckoning calculations at 1 kHz allowing accurate capture of high frequency motions. Xsens' industry-leading sensor fusion algorithm provides high accuracy and sensor auto-calibration in a cost-effective module for a wide range of (embedded) outdoor applications. It relieves users from the design, integration and maintenance of gyroscopes, accelerometers and other sensors.

The MTi-7 is supported by the MT Software Suite which includes MT Manager (GUI for Windows/Linux), SDK, example codes and drivers for many platforms including ROS.



- 3D models available on request

This document is informational and not binding.
Complete and detailed specifications are available at
mtidocs.movella.com

Sensor fusion performance

Roll, Pitch	0.5 deg RMS
Yaw/Heading	1.5 deg RMS
Position	1 m CEP ¹
Velocity	0.05 m/s RMS

Gyroscope

Standard full range	2000 deg/s
In-run bias stability	6 deg/h
Bandwidth (-3dB)	230 Hz
Noise Density	0.003 °/s/√Hz

Accelerometer

Standard full range	16 g
In-run bias stability	40 µg
Bandwidth (-3dB)	230 Hz
Noise Density	70 µg/√Hz

Magnetometer

Standard full range	+/- 8 G
Total RMS noise	0.5 mG
Non-linearity	0.2%
Resolution	0.25 mG

GNSS Receiver

GNSS receiver interface	UART (NMEA, UBX, beta:SBF/GSOF)
GNSS precision	Standard

Barometer

Barometer interface	Yes (SPI)
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Mechanical

IP-rating	IP00
Operating Temperature	-40 to 85 °C
Casing material	PCB
Mounting orientation	No restriction, full 360° in all axes
Dimensions	12.1 x 12.1 x 2.55 mm
Connector	SMD, footprint compatible with JEDEC PLCC-28
Weight	0.6 g
Certifications	CE, FCC, RoHS

Electrical

Input voltage	2.8 to 3.6V
Power consumption (typ)	<150 mW @ 3V

Interfaces / IO

Interfaces	UART, SPI, I²C
Sync Options	Yes
Protocols	Xbus, NMEAin
Clock drift	1 ppm (external)
Output Frequency	Up to 1 kHz
Built-in-self test	Gyr, Acc, Mag, Baro, GNSS

Software Suite

GUI (Windows/Linux)	MT Manager Firmware updater, Magnetic Field Mapper
SDK (Example code)	C++, C#, Python, Matlab, Nucleo, public source code
Drivers	LabVIEW, ROS, GO
Support	Online manuals, community and knowledge base

¹ GNSS receiver from DK is used, depending on GNSS conditions.